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# A Byzantine Agreement Protocol for Game Theorists

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#### Abstract

We introduce a new Byzantine agreement protocol consisting of two stages of private communication which substitutes public communication (broadcasting to all the players) in a very strong sense. At every information set, players hold the following consistent beliefs (Kreps and Wilson (1982)): every player believes, no matter what messages she has sent or received, that the bitwise-majority message of every player is the same. We provide applications of our result.

KEYWORDS: Byzantine agreement, broadcasting, public communication, consistent beliefs JEL CLASSIFICATION: C72; D82.

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#### 1 Introduction

Public and private communication are essential in real life, hence, in many economic settings, and also in computer science. One advantage of public communication is that its outcome is commonly known among the players (by definition) who can then condition and coordinate their future play on this outcome.<sup>1</sup> Clearly, private communication is essential when there are more than two players. Public communication cannot replace the private one. What if players cannot communicate publicly but can only use pairwise private communication channels? Is it possible to replace public communication with private communication in a way that players at least *always believe* that all the other players consider the same outcome of the given private communication?

First, we consider only the case of n = 4 players, P0, P1, P2, and P3, and unilateral deviations. Then in section 5, we generalize our result to  $n \ge 4$  players and unilateral deviations. <sup>2</sup> Suppose P3 (the sender) would like to publicly announce an element of a finite set  $x \in X$ , each chosen with equal probability, but broadcasting is not possible. For example, Lamport, Shostak, and Pease (1982) describe a Byzantine agreement protocol using private communication channels as follows. In stage 1, P3 sends the message x to players P0, P1, and P2. In stage 2, P0, P1, P2 (the forwarders) forward the message they received in stage 1 to each other, i.e., to P0, P1, and P2 but not to P3. Players then make a choice which depends on the messages they have sent and received. Lamport et al. (1982) suggest two possible choices rule. In both cases the forwarders only use their three received messages and the sender uses the three messages she sent in stage 1. In choice rule (a), players' choice is the median of these messages. In choice rule (b), players' choice is the majority of the messages if it exists and otherwise they choose some fixed, commonly known  $z \in X$ .

The above protocol is *resilient* in the following sense. If only one of the players deviates from the protocol, all the players choose the same element of X and this choice is the message sent by the sender if she does not deviate from the protocol. We would like to have the following stronger version of resilience which we call *belief-resilience*: (1) the protocol is resilient; (2) in any information set, all the players believe that the choices of all the players coincide; (3) (i) the beliefs are consistent with the protocol in the sense of Kreps and Wilson (1982), and (ii) point (2) also holds conditional on that the players know what message the sender was expected to send. While points (1), (2), and (3)(i) are natural requirements, we provide an application demonstrating the importance of (3)(ii) below. Or simply think of a situation in which, besides P3, another player also knows the value of x.

<sup>&</sup>lt;sup>1</sup>See the importance of public communication from another aspect in Farrell and Gibbons (1989).

<sup>&</sup>lt;sup>2</sup>It can be shown that three players cannot replace broadcast with private communication in a (1-)resilient way (see Pease, Shostak, and Lamport (1980)). We are motivated by sequential equilibrium that considers deviations by a single player. The case of more than one deviators is left for future research.

#### 2 Example

To demonstrate the notion of belief-resilience, let  $X = \{0, 1, 2\}$  and z = 1 in which case choice rules (a) and (b) coincide. Suppose that the sender deviates from the protocol and sends three different messages to the forwarders in stage 1. Suppose that forwarder Pi receives the message *i*. Further suppose that forwarder P1 sends 0 to P0 and P2 (instead of sending 1 to both) while P0 and P2 correctly forward stage 1 messages of the sender to each other and to P0. Players use the following triplets of messages when making a choice: P0 uses (0,0,2), P1uses (0,1,2), P2 uses (0,0,2), and P3 uses (0,1,2). Then, according to the protocol of Lamport et al. (1982), P1 and P3 choose 1, P0 and P2 choose 0. It is clear that P3 should believe that all the forwarders choose 1 because she must believe that forwarders follow the protocol. But what should P0, P1, and P2 believe in their corresponding information sets?

According to (2), P0 should believe that P1, P2, and P3 choose 0. To satisfy (3), we will argue that P0 should believe that P3 has sent 0 to P1 and P2 and it is only P2 who has sent her the wrong message 2 instead of 0. According to (2), P2 should believe that P0, P1, and P3 choose 0. To satisfy (3), we will argue that P2 should believe that P3 has sent 0 to P0 and P1 and it is only P3 who has sent her the wrong message 2 instead of 0. According to (2), P1 should believe that P0, P2, and P3 choose 1. P1 cannot believe that P3 has sent *i* to P*i* for i = 0, 2 because then she should also believe that P0 and P2 will choose 0 (the majority of their messages). This is because she must believe that P1 should believe that P3 has sent 1 to P0 and P2 and both of them. To satisfy (3), we will argue that P1 should believe that P3 has sent 1 to P0 and P2 and both of them have forwarded a wrong message to her, namely, P0 has sent 0 and P2 has sent 2 to P1 instead of 1.

Tedious calculations show that the protocol of Lamport et al. (1982) under both choice rules is belief-resilient in this example when X is small.<sup>3</sup> We conjecture that the protocol of Lamport et al. (1982) with choice rule (a) is not belief-resilient when X is large, but it is always beliefresilient with choice rule (b) as long as the number of players is four.<sup>4</sup>

In this paper we offer a new choice rule, which we call *bitwise-majority*, with which the

 $<sup>^{3}</sup>$ A natural candidate, paranoid beliefs à la Geffner and Halpern (2024) does not work. It would make the forwarders always believe that all the three of them have received the same message in stage 1 and, hence, choices could not follow the majority of the messages. Moreover, a deviating sender would then believe that the forwarders' choices differ and, in fact, could induce different choices of the forwarders.

<sup>&</sup>lt;sup>4</sup>We do not know, whether Lamport et al. (1982) mean that z = RETREAT should be understood as an element of X, i.e., whether the choices must always be in X or they only have to coincide. When  $z \notin X$  and the definition of resilience is modified accordingly, then their protocol is clearly not belief-resilient with choice rule (b). P1 should believe the others also see three different messages and choose z. But then she should also believe that P3 has sent different messages to the different players which means that she believes that both P0 and P2 will choose 0 given the messages that P1 has sent them. Also, as we will see in section 5, not just our choice rule, but even our protocol is different from Lamport et al. (1982) when the number of players is more than four.

protocol of Lamport et al. (1982) is belief-resilient in the case of four players. We deviate from the protocol of Lamport et al. (1982) when the number of players is more than four and show that our new protocol with our new choice rule is still belief-resilient. We prove these by constructing a sequence of completely mixed strategies, the so-called justifying sequence (Kreps and Wilson (1982)), converging to our protocol.<sup>5</sup> We calculate beliefs along the sequence at all information sets using the Bayes rule and show that the limits of these beliefs satisfy (2) and (3) ((1) will be trivially satisfied).

#### **3** The formal statement for n = 4

Let I denote the set of players with |I| = n = 4. Without loss of generality, let X be a finite set containing all the binary numbers of n bits (digits) and let  $\mu \in \Delta(X)$  be a given probability distribution over X with full support.<sup>6</sup> Let  $S = R_i = X^3$ ,  $S_i = X^2$ , C = X,  $H_3 = S$ ,  $H_i = R_i \times S_i$ for i = 0, 1, 2. C is the set of possible choices, S is the set of triplets P3 can send in stage 1,  $R_i$ is the set of triplets Pi receives in stages 1 and 2,  $S_i$  the set of couples that forwarder Pi can send to the other forwarders in stage 2, and  $H_i$  is the set of messages sent and received by Pi for  $i \in I$ . We denote generic elements of these sets as follows:  $x \in X, s \in S, r_i \in R_i, s_i \in S_i, h_i \in H_i$ . Let  $m: X^3 \to C$  be the function which associates to every triplet of binary numbers the choice of a player: the binary number is obtained by considering the bitwise (or digit-wise) majority value of the values of the given bit (digit) in the triplet. Extend m to  $H_i$  using  $R_i$ , i.e., the messages that Pi has received for i = 0, 1, 2, and using S, i.e., the messages she sent for i = 3. Let  $\sigma$  denote the protocol of Lamport et al. (1982) and consider m as the associated choice rule. Formally  $\sigma_3: X \to \Delta(S)$  and  $\sigma_i: X \to \Delta(S_i)$  for i = 0, 1, 2, where  $\Delta(Y)$  denotes the probability distributions over a finite set Y. Notice that  $\sigma$  here is deterministic.  $\sigma$  is clearly resilient under the choice rule m. A completely mixed strategy  $\sigma_i^k$  of Pi is a protocol for Pi such that in any of her information sets, every message profile that Pi can send to the other players, has positive probability under  $\sigma_i^k$ , i.e.,  $\sigma_i^k(x)$  is in the interior of the corresponding set of probability distributions. Consider a sequence of completely mixed strategy profile  $\sigma^k$  converging to  $\sigma$ which is called the justifying sequence. Clearly, given  $\mu$  and m there is an induced probability distribution  $P_{\sigma^k}$  over  $X \times \prod_{i \in I} (H_i \times C)$ , i.e., over the set of possible realizations of x, the set of histories of the players and over their final choices. Clearly,  $P_{\sigma^k}(x, h_i) > 0$  for all  $h_i \in H_i$ , for all

<sup>&</sup>lt;sup>5</sup>The justifying sequence for choice rule (b) is necessarily asymmetric in that it must treat different messages differently. We do not know how to construct such a justifying sequence in general, when X is large.

<sup>&</sup>lt;sup>6</sup>If X does not contain all the binary numbers using n bits, then let  $X_b$  be the set of all binary numbers using n bits and  $f: X_b \to X$  be a surjective function. Modify the protocol of Lamport et al. (1982) so that whenever the sender sends  $x \in X$  to the other three players, let the sender now instead randomize over all  $y \in f^{-1}(x)$  with positive probability.

 $x \in X$ , and for all  $i \in I$ . Let us define:

$$P(m(h_j)|x, h_i) = \lim_{k \to \infty} P_{\sigma^k}(m(h_j)|x, h_i)$$
$$P(x|h_i) = \lim_{k \to \infty} P_{\sigma^k}(x|h_i),$$
$$P(m(h_j)|h_i) = \lim_{k \to \infty} P_{\sigma^k}(m(h_j)|h_i).$$

**Theorem 1.** There exists a sequence of completely mixed strategies  $(\sigma^k)_{k \in \mathbb{N}}$  converging to  $\sigma$ such that for all  $i, j \in I$ , for all  $h_i \in H_i, h_j \in H_j$ , and for all  $x \in X$  we have that  $P(m(h_j) = m(h_i)|h_i) = P(m(h_j) = m(h_i)|h_i, x) = 1$ . We also have that  $P(x = m(h_i)|h_i) = 1$ . Notice, that these probabilities do not depend on the messages sent by forwarder  $P_i$ , i.e., on  $s_i$ .

**Remark 1.** We note that our theorem also holds if players have heterogenous priors over X not necessarily with full support. Then one can consider any  $x \in X$  for which  $\mu_i(x) > 0$ .

#### 4 The proof of the theorem

We construct  $\sigma_i^k$  as follows. Whenever  $\sigma_3$  specifies for the sender to send the message profile  $(x, x, x) \in S$  to the other players in stage 1, i.e., when x has been selected according to  $\mu$ , the sender selects a message profile to be sent in the following way. The sender randomizes independently across the bits over the triplets of bits she sends using the following probabilities. Suppose that *l*th bit of x is 0. Then the sender selects the triplet of bits (0,0,0) with probability close to 1, selects (1,1,1) with probability in the order of  $\epsilon^e$ , selects (1,0,0), (0,1,0), (0,0,1) in the order of  $\epsilon^b$ , and selects (0,1,1), (1,1,0), (1,0,1) in the order of  $\epsilon^c$ . The error probabilities are symmetric if the *l*th bit of x is 1. Forwarders forward the wrong bit to any forwarder independently across forwarders and across bits (digits) in the order of  $\epsilon^a$ . We specify the values of a, b, c, e > 0 later. Let  $\epsilon = 1/k$ , then  $\sigma^k \to \sigma$  as  $k \to \infty$ .

Now, it is sufficient to show that our theorem holds for  $X = \{0, 1\}$  because the randomization of the players are independent across the bits conditional on x. To see this:  $P(m_j, m_i|x) = \prod_{1 \le l \le n} P(m_j^l, m_i^l|x^l) = \prod_{1 \le l \le n} P(m_j^l, m_i^l|x^l)$ , where the superscript l denotes the lth bit of the object and  $m_j, m_i$  stand for  $m(h_j), m(h_i)$ . Also,  $P(m_j, m_i) = \sum_{x \in X} P(m_j, m_i|x) \mu(x) = \sum_{x \in X} \mu(x) \prod_{1 \le l \le n} P(m_j^l, m_i^l|x^l)$ . From now on we assume that  $X = \{0, 1\}$ .

Our conditions in the theorem about the beliefs of the sender are trivially satisfied because those can be calculated by assuming that the forwarders follow the protocol, i.e., they forward the bit which was sent by the sender. For the forwarders it is sufficient to show that they believe, given  $h_i$ , that the sender has sent  $m(h_i)$  to the other forwarders. This is because Pi must believe that the other forwarders forwarded the correct message to each other and, hence, they receive the message  $m(h_i)$  from the sender and from the other forwarder and therefore, their choice is  $m(h_i)$  irrespective of what Pi forwards.

To this end, let us assume that x = 0. We construct the table below. The case of x = 1 is symmetric by construction, i.e., one only has to swap the 0-s and the 1-s in the table. Clearly, the belief of forwarder Pi about  $s \in S$  does not depend on  $s_i$ . Hence, consider the eight possible triplets  $r_i \in R_i$  that a forwarder  $P_i$  can receive, one by one, and the order of the joint probabilities, conditional on x = 0, of the corresponding four possible triplets  $s \in S$  that the sender may have sent (one of the coordinates of the triplets is fixed by the message Pi has received from the sender). In the table below, the first coordinate in any triplet is the bit that  $P_i$  has received from the sender and we do not make a difference which forwarder sends a bit different from what Pi has received from the sender, hence, we only have six cases for  $r_i$ . We also do not make a difference which forwarder has sent a bit to Pi different from what she has received from the sender, hence, for each  $r_i$  we only have three possible s. Let us choose e = 4, b = 13, c = 14 and a = 8 to satisfy e + a < b < c < 2a which will imply our theorem. Intuitively, these choices of probabilities ensure: that two forwarders forward the wrong bit to the same forwarder is infinitely less likely than that the sender has sent the wrong bits to two of the forwarders which is infinitely less likely than that the sender has sent the wrong bit to one of the forwarders which is infinitely less likely than that the sender has sent the wrong bit to all the forwarders and one of the forwarders forwarded a bit different from what she received. Given that e + a < b < c < 2a, we have that always the first (bold) triplet of s, given  $r_i$ , converges to 0 in the slowest order. Hence, the first statement of our theorem follows.

Finally, to prove that  $P(x = m(h_i)|h_i) = 1$ , it is enough to see that  $P(x = m(h_i)|h_i) = P(x = m(r_i)|r_i) = 1$ , where  $h_i = (r_i, s_i)$  and that  $\lim_{k\to\infty} \frac{P_{\sigma^k}(r_i|x\neq m(r_i))}{P_{\sigma^k}(r_i|x=m(r_i))} = 0$ . This is true because both the numerator and the denominator converge to 0 in the order of the slowest corresponding s. Direct calculation from the table below (and from the one where the 0-s and the 1-s are

swapped) verifies our statement.

$r_i$	order of $P_{\sigma^k}(s, r_i   x = 0)$	s
$(0,\!0,\!0)$	0	$(0,\!0,\!0)$
	е	$(1,\!1,\!1)$
(1, 1, 1)	c+a	$(1,\!0,\!1)$
	b+2a	(1,0,0)
	e+a	$(1,\!1,\!1)$
(1,0,1)	С	$(1,\!0,\!1)$
	b+a	$(1,\!0,\!0)$
(0,1,1)	С	(0,1,1)
	2a	$(0,\!0,\!0)$
	b+a	$(0,\!1,\!0)$
	a	$(0,\!0,\!0)$
$(0,\!1,\!0)$	b	$(0,\!1,\!0)$
	c+a	(0,1,1)
	b	(1,0,0)
$(1,\!0,\!0)$	e+2a	$(1,\!1,\!1)$
	c+a	$(1,\!0,\!1)$

## 5 Generalization of the theorem to n > 4

Suppose that besides P0, P1, P2, P3 there are other players:  $P4, \ldots, P(n-1)$ . It is still P3 who wants to publicly announce some  $x \in X$ . We complement  $\sigma$  above with the following. In stage 2, players P0, P1, P2 forward their messages received from P3 to players  $P4, \ldots, P(n-1)$ . The latter players do not receive any message from P0 in stage 1 and they do not send any message in stage 2. However, given the received messages from players P0, P1, P2, players  $P4, \ldots, P(n-1)$  apply the bitwise majority choice on these messages. We note that this protocol is different from Lamport et al. (1982).<sup>7</sup> The protocol is clearly resilient. Suppose that P0, P1, P2, P3 make mistakes as specified previously, but P0, P1, P2 never make a mistake when forwarding their messages to  $P4, \ldots, P(n-1)$ .<sup>8</sup> The beliefs of  $P4, \ldots, P(n-1)$  can already be calculated using the Bayes rule. They will believe that the messages they received are the ones that P3 has sent to P0, P1, P2. It follows that the beliefs of these players about

<sup>&</sup>lt;sup>7</sup>We do not know how to specify the choice rule and the justifying sequence for the protocol of Lamport et al. (1982) when n > 4. They require that the sender sends the message to all the other players and these players forward the message to each other in stage 2.

<sup>&</sup>lt;sup>8</sup>Alternatively, assume that these error probabilities converge to 0 in a sufficiently fast order so that these players believe that it is P0 who has deviated.

the other players' choices satisfy our theorem. Also, the beliefs of P0, P1, P2, P3 about the choices of  $P4, \ldots, P(n-1)$  satisfy our theorem, because, as before, P3 believes that P0, P1, P2 forward her messages correctly, and any forwarder from P0, P1, P2 believes that the other two forwarders received the bitwise majority of her messages and that they have forwarded this message to  $P4, \ldots, P(n-1)$ .

## 6 Applications and further properties

#### 6.1 Two applications to Gerardi (2004)

Our theorem can be directly applied to theorem 1 in Gerardi (2004). In his theorem 1, Gerardi (2004) implements the set of correlated equilibria as sequential equilibria of a game, extended with unmediated communication with five (or more) players. Gerardi (2004) assumes that at the very first stage of this extended game, a player can broadcast a message to either three or two other players. From our theorem, it is clear how to mimic broadcasting when the number of involved players is four, consisting of the sender and three forwarders. It is also easy to mimic a broadcasting to two players, i.e., when only three players are involved, but there are in fact five players in the game. Assume that P0 wants to mimic a broadcast of  $x \in X$  to players P1 and P2. Let P0 choose  $y \in X$  uniformly and let  $z \in X$  be such that  $y + z \mod |X| = x$ . Let P0 mimic the public announcement of y using players P1, P2, P3 and do the same with z using players P1, P2, P4. Then P3 and P4 obtain no information about x but P1 and P2 can calculate x.

In his theorem 2, Gerardi (2004) uses Forges (1990) to implement the set of (regular) communication equilibria in sequential equilibria of a game, extended with unmediated communication with five players. However, Forges (1990) and, hence, Gerardi (2004) assume that a player can make a public announcement to the other four players. This case is covered by our generalization of our theorem in section 5.

We note that by remark 1, it does not matter when the public communication takes place in an extensive form game. Also, if at some successive information sets, a player receives an information which seemingly contradicts to her beliefs about the past choices of the other players, this can always be explained by deviations outside the mimicking-public-announcement phase by choosing the error probabilities during the mimicking phase sufficiently small.

#### 6.2 Further properties

The importance of (3)(ii) which is implied by our theorem can be demonstrated with the following situation. Suppose that there is another player, say P2 besides P3, who also knows

the value of x. We clearly need (3)(ii). Furthermore, suppose that P2 also uses the corresponding variant of  $\sigma$  to transmit the value of x. Let us denote by  $\sigma^2$  and  $\sigma^3$  the protocols of P2 and P3. We also use superscripts 2 and 3 for the histories, and sent and received messages corresponding to  $\sigma^2$  and  $\sigma^3$ , respectively. What if P1 observes  $h_1^2, h_1^3$  such that  $m(h_1^2) \neq m(h_1^3)$ ? (a) What is  $P(m(h_j^2) = m(h_1^2), m(h_j^3) = m(h_1^3)|h_1^2, h_1^3)$ ? We claim it can be equal to 1. (b) What does P1 believe about the true value of x? Can P1 always believe for example in the transmission of P2? Namely, can we have that  $P(x = m(h_1^2)|h_1^2, h_1^3) = 1$  for any  $h_1^2, h_1^3$ ? An application of the answer to this question, which is affirmative, can be found in Āzacis, Laclau, and Vida (2025).

We now prove points (a) and (b). To this end, assume that the completely mixed sequences converging to  $\sigma^2$  and  $\sigma^3$  are the same (once the players' roles are permuted accordingly), possibly with different values for  $a^i, b^i, c^i, e^i$  for i = 2, 3 (with  $e^i + a^i < b^i < c^i < 2a^i$ ), but are independent conditional on (the bits of)  $x \in X$ . Let  $P_{\sigma^{2k},\sigma^{3k}}$  be the induced distribution over  $X \times (\prod_{i \in I} (H_i \times C))^2$ .

For (a), we claim that  $P(m(h_i^2) = m(h_1^2), m(h_i^3) = m(h_1^3)|h_1^2, h_1^3) = 1$ . To see this define:

$$P_{\sigma^2}(m(h_j^2)|x,h_1^2) = \lim_{k \to \infty} P_{\sigma^{2^k}}(m(h_j^2)|x,h_1^2),$$

and  $P_{\sigma^3}(m(h_j^3)|x, h_1^3)$  similarly. Define

$$P(m(h_j^2), m(h_j^3)|x, h_1^2, h_1^3) = \lim_{k \to \infty} P_{\sigma^{2^k}, \sigma^{3^k}}(m(h_j^2), m(h_j^3)|x, h_1^2, h_1^3)$$

which is equal to

$$\lim_{k \to \infty} P_{\sigma^{2k}}(m(h_j^2)|x, h_1^2) P_{\sigma^{3k}}(m(h_j^3)|x, h_1^3) = P_{\sigma^2}(m(h_j^2)|x, h_1^2) P_{\sigma^3}(m(h_j^3)|x, h_1^3).$$

Then define:

$$\begin{split} P(m(h_j^2), m(h_j^3) | h_1^2, h_1^3) &= \lim_{k \to \infty} P_{\sigma^{2^k}, \sigma^{3^k}}(m(h_j^2), m(h_j^3) | h_1^2, h_1^3) \\ P(x | h_1^2, h_1^3) &= \lim_{k \to \infty} P_{\sigma^{2^k}, \sigma^{3^k}}(x | h_1^2, h_1^3). \end{split}$$

Hence we have that:

$$P(m(h_j^2) = m(h_1^2), m(h_j^3) = m(h_1^3)|h_1^2, h_1^3) = \sum_{x \in X} P(m(h_j^2) = m(h_1^2), m(h_j^3) = m(h_1^3)|x, h_1^2, h_1^3) P(x|h_1^2, h_1^3)$$
$$= \sum_{x \in X} P_{\sigma^2}(m(h_j^2) = m(h_1^2)|x, h_1^2) P_{\sigma^3}(m(h_j^3) = m(h_1^3)|x, h_1^3) P(x|h_1^2, h_1^3) = \sum_{x \in X} P(x|h_1^2, h_1^3) = 1.$$

$$=\sum_{x\in X} P_{\sigma^2}(m(h_j^2) = m(h_1^2)|x, h_1^2) P_{\sigma^3}(m(h_j^3) = m(h_1^3)|x, h_1^3) P(x|h_1^2, h_1^3) = \sum_{x\in X} P(x|h_1^2, h_1^3) = 1$$

where in the penultimate equality we applied our theorem for  $P_{\sigma^2}$  and for  $P_{\sigma^3}$ .

For (b), we can still assume that  $X = \{0, 1\}$ . In case  $m(h_1^2) = m(h_1^3)$ , P1 must believe that

 $x = m(h_1^2) = m(h_1^3)$  with probability 1.<sup>9</sup> Suppose that  $x = m(h_1^2) \neq m(h_1^3)$ . Clearly, the answer will depend on the values  $a^i, b^i, c^i, e^i$  for i = 2, 3, i.e., it depends on which player makes mistakes with larger probability. Let us write

$$P(x|h_1^2, h_1^3) = P(x|r_1^2, r_1^3) = \lim_{k \to \infty} \frac{P_{\sigma^{2k}}(r_1^2|x) P_{\sigma^{3k}}(r_1^3|x) \mu(x)}{\sum_{x' \in X} P_{\sigma^{2k}}(r_1^2|x') P_{\sigma^{3k}}(r_1^3|x) \mu(x')}$$

We want this limit to be 1, for  $x = m(h_1^2)$ , i.e., P1 believes that the transmission of P2 is true (and P3 deviated). What we need is that:

$$\lim_{k \to \infty} \frac{P_{\sigma^{2k}}(r_1^2 | x') P_{\sigma^{3k}}(r_1^3 | x')}{P_{\sigma^{2k}}(r_1^2 | x) P_{\sigma^{3k}}(r_1^3 | x)} = 0$$

for  $x' \neq x$ .<sup>10</sup> Suppose w.l.o.g. that  $0 = m(h_1^2) = x \neq x' = m(h_1^3) = 1$ . We can show that

$$\frac{P_{\sigma^{2k}}(r_1^2|1)}{P_{\sigma^{2k}}(r_1^2|0)} \frac{P_{\sigma^{3k}}(r_1^3|1)}{P_{\sigma^{3k}}(r_1^3|0)} < 1/k \tag{1}$$

by using the table in the proof of our theorem, and choosing  $h_1^2$  and  $h_1^3$  to upper bound the two factors independently, and with appropriately choosen  $a^i, b^i, c^i, e^i$  for i = 2, 3. The tedious calculation can be found in section A of the Appendix.

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<sup>&</sup>lt;sup>9</sup>This immediately follows from our theorem where this is true in case of a single sender. <sup>10</sup>When X is larger, we have to consider the factors of  $\lim_{k\to\infty} \prod_{1\leq l\leq n} \frac{P_{\sigma^{2k}}(r_1^{2l}|x^l)P_{\sigma^{3k}}(r_1^{3l}|x^l)}{P_{\sigma^{2k}}(r_1^{2l}|x^l)P_{\sigma^{3k}}(r_1^{3l}|x^l)} = 0$ , where  $r_1^{2l}$ is the triplet obtained by using the lth digits of the triplet  $r_1^2$ .

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#### A The proof of inequality 1

All the four probabilities appearing in inequality 1 can be written as sums with respect to the corresponding  $s^2$  and  $s^3$ . For example,  $P_{\sigma^{2k}}(r_1^2|1) = \sum_{s^2} P_{\sigma^{2k}}(r_1^2, s^2|1)$ . In the limit only the terms with the smallest exponents determine the value of the product. Consider the table in the proof of our theorem. The table should be read as follows. All 0-s and 1-s are swapped (because x = 1),  $r_i = r_1^2$ , and  $s = s^2$ . The term with the smallest exponent is the first (bold) triplet in the table in the column of s given  $r_i$ . We consider all possible realizations of  $r_1^2$ . Consider  $r_1^2 = (1, 0, 0)$ . Then the probability corresponding to  $s^2 = (1, 0, 0)$  has the smallest exponent both under x = 1 and under x = 0 (change back the 0-s and 1-s). Then,  $\frac{P_{\sigma^{2k}}(r_1^2|1)}{P_{\sigma^{2k}}(r_1^2|0)} \approx \frac{P_{\sigma^{2k}}(s^2, r_1^2|1)}{P_{\sigma^{2k}}(s^2, r_1^2|0)} \approx \epsilon^{c^2-b^2}$ . Consider  $r_1^2 = (0, 0, 0)$ . Then the probability corresponding to  $s^2 = (1, 0, 0, 0)$  has the smallest exponent under x = 0 and x = 1. Then,  $\frac{P_{\sigma^{2k}}(r_1^2|1)}{P_{\sigma^{2k}}(r_1^2|0)} \approx \epsilon^{e^2}$ . Finally, consider  $r_1^2 = (0, 1, 0)$ . Then the probability corresponding to  $s^2 = (0, 0, 0)$  has the smallest exponent under both x = 0 and x = 1. Then,  $\frac{P_{\sigma^{2k}}(r_1^2|1)}{P_{\sigma^{2k}}(r_1^2|0)} \approx \epsilon^{e^2}$ . For  $r_1^3$  one can do the same exercise and get that either  $\frac{P_{\sigma^{3k}}(r_1^3|1)}{P_{\sigma^{3k}}(r_1^3|0)} \approx \epsilon^{-(c^3-b^3)}$  or  $\frac{P_{\sigma^{3k}}(r_1^3|1)}{P_{\sigma^{3k}}(r_1^3|0)} \approx \epsilon^{-e^3}$ . If  $\min(c^2 - b^2, e^2) > \max(c^3 - b^3, e^3)$ , then we have that the factor converges to 0. This is satisfied if we choose  $a^3, b^3, c^3, e^3$  to be a, b, c, e as above (a = 8, b = 13, c = 14 and e = 4) and choose  $a^2, b^2, c^2, e^2$  to be 5a, 5b, 5c, 5e  $(20 = 5e^3 = e^2 > \min(c^2 - b^2, e^2) = c^2 - b^2 = 5(c^3 - b^3) = 5 > e^3 = 4$ ).